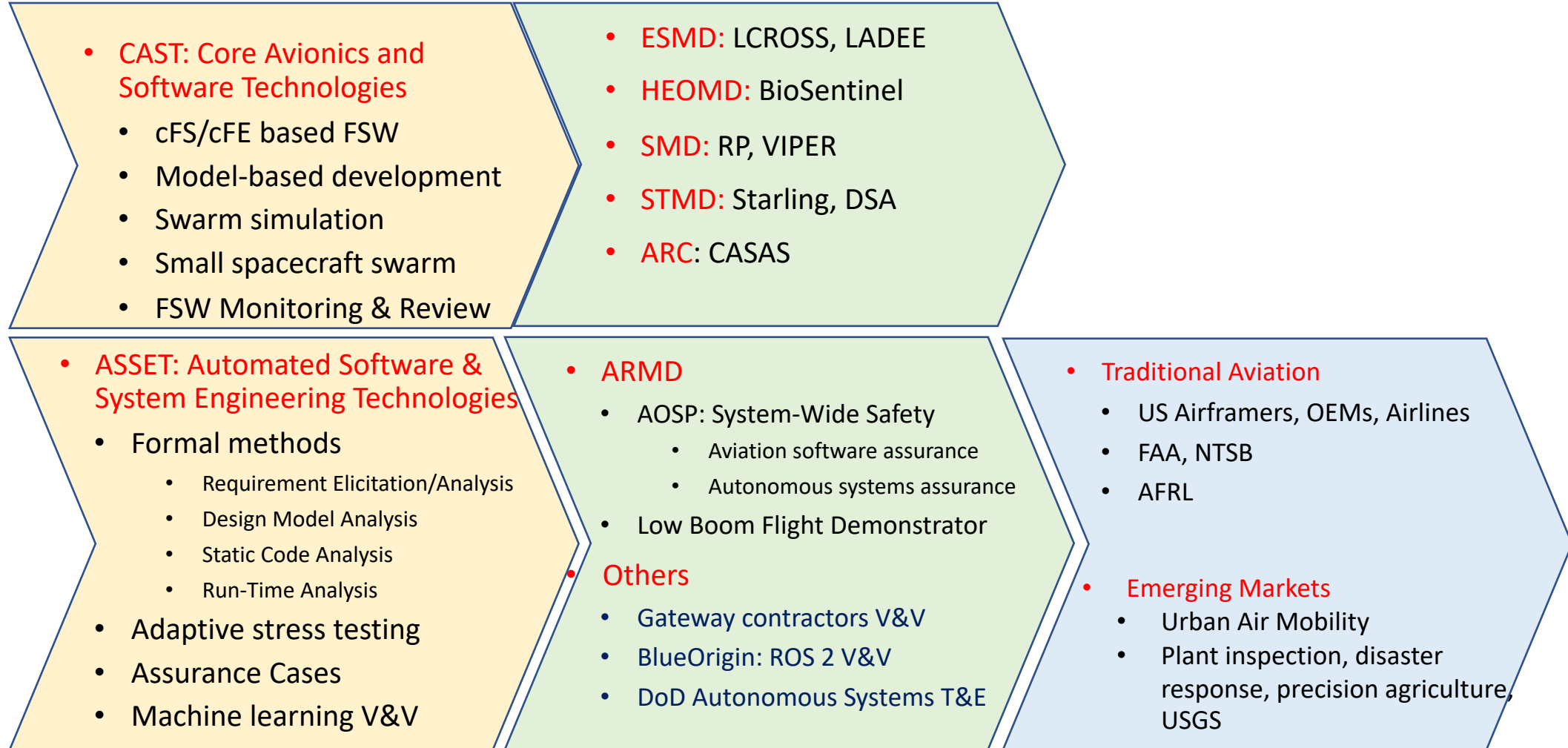


V&V for Autonomy

Dr. Guillaume Brat
NASA Ames Research Center
Intelligent Systems Division
Robust Software Engineering



Introduction





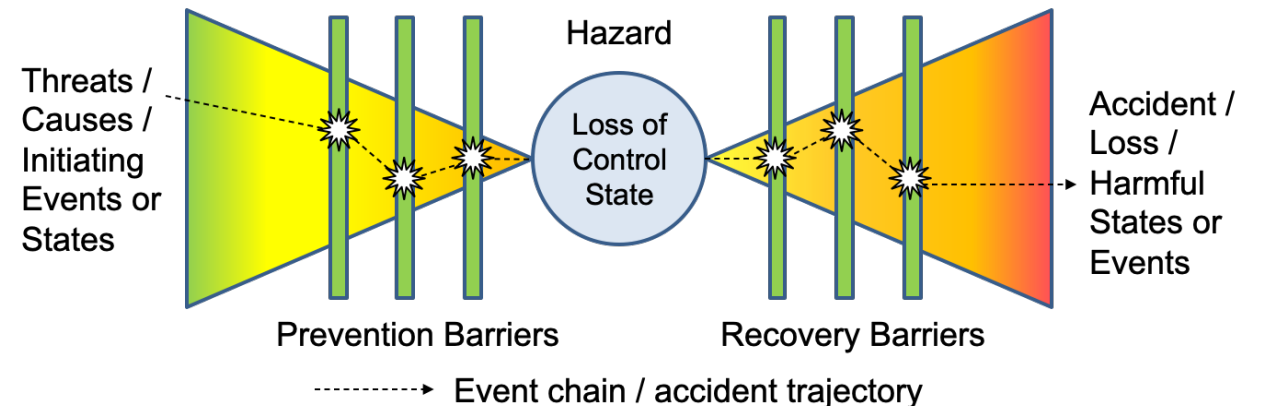
Focus elements

- Our strategy for the V&V of autonomy is focusing on the following elements:
 - Explaining why a system is safe, and remains safe in operations, through dynamic safety cases
 - Identifying more hazards, especially when a system is complex or adapting to changing conditions
 - Formalizing requirements to facilitate safety analysis and traceability
 - Computing “provenly” safe bounds of operations
 - Addressing verification of machine learning components

Dynamic Safety Cases

‘A safety case is a structured argument, supported by a body of evidence, that provides a compelling, comprehensible and valid case that a system is safe for a given application in a given operating environment’
- NASA System Safety Handbook ver. 1 (2014)

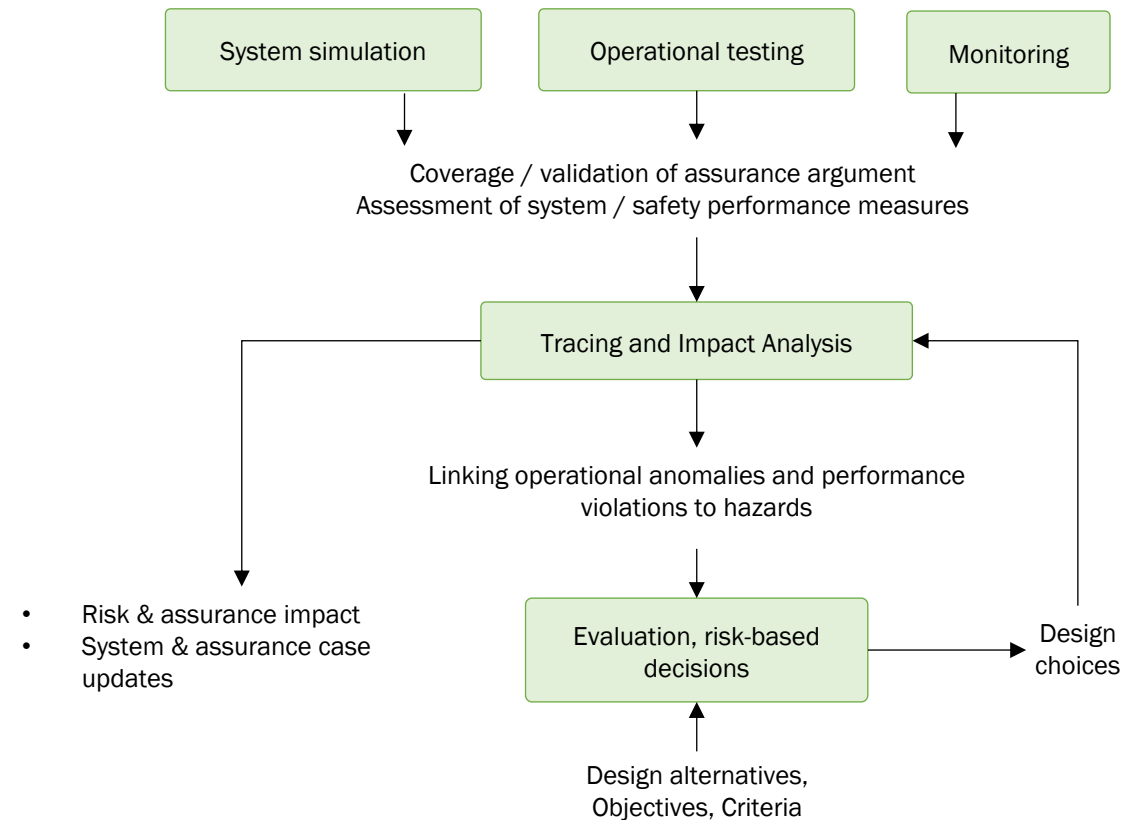
- We have developed a tool called AdvoCATE for creating and visualizing safety cases
- AdvoCATE Barrier models
 - Risk scenarios showing chain of events leading to accidents, loss, or harm
 - Represented using Bow Tie Diagrams
 - Barrier = Risk reduction mitigation
 - Prevention or recovery function
 - Reduction of event probability and severity





Dynamic Safety Cases

- Extend AdvoCATE into a dynamic dashboard to reason about safety during operations and support risk-based decision making
- Integration of risk-based design, development, and assurance in AdvoCATE
- Demonstrated in March 2021 on a centerline tracking example implemented with DNNs





- SmallSat Conference 2021





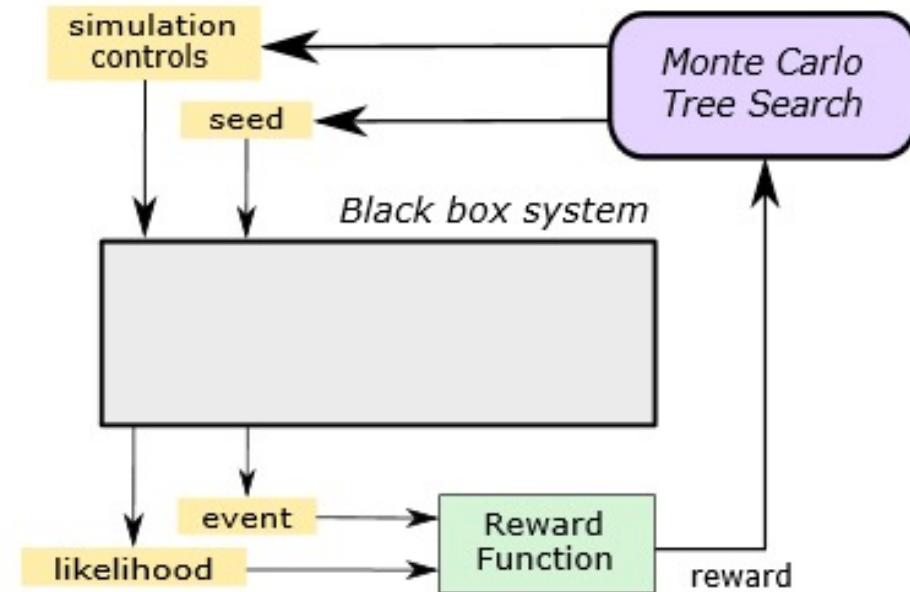
Identifying More Hazards

- Identifying more hazards, especially when a system is complex or adapting to changing conditions
 - Adaptive Stress (AdaStress) testing
 - Functional and fault modelling with Fmdtools
 - Use of NLP for mining historical data and identify hazards that are often overlooked



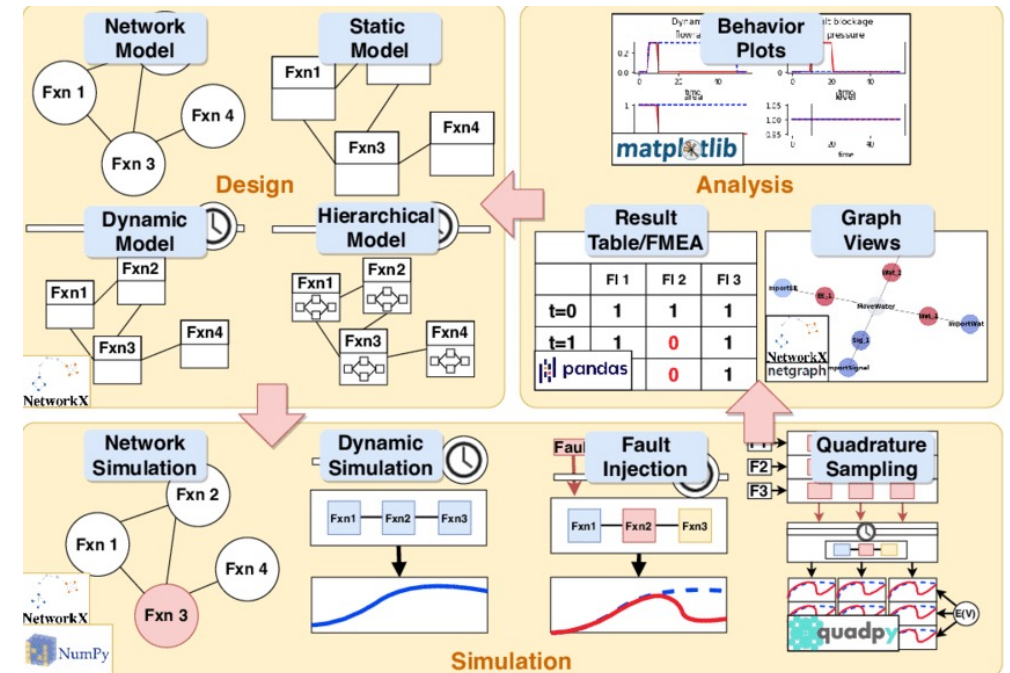
Identifying More Hazards: AdaStress

- AdaStress (Adaptive Stress testing) is a software package for an accelerated simulation-based stress testing method for finding the most likely path to a failure event
- It has been successfully demonstrated to industry
 - It has been adopted by GE Aviation Systems and is being incorporated in their continuum testing environments.



Identifying More Hazards: Fmdtools

- Fmdtools (Fault Model Design *tools*) is a design and analysis environment, which enables a designer to
 - represent the system in the early design process,
 - simulate the effects of faults, and
 - quantify corresponding resilience metrics.





Formalizing Requirements

- We have developed a tool called FRET that allows a user to specify requirements in a quasi-natural language in order to formalize them into various logics
- This helps support formal analysis in later stages of the development process
 - E.g., for formalizing requirements that we want to prove on Simulink models using the CoCoSim tool.
- It also allows us to perform formal analysis on requirements
 - E.g., detecting inconsistencies between requirements



Formalizing Requirements

Requirement ID
FSM-001

Parent Requirement ID

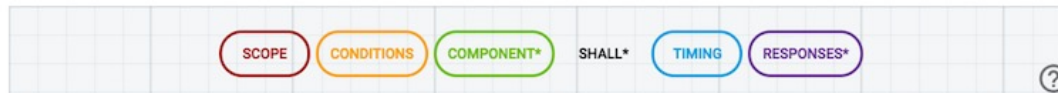
Project
LM_requirements

Rationale

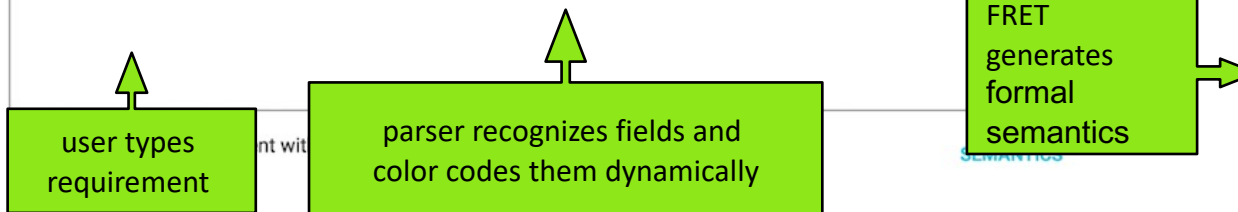
Exceeding sensor limits shall latch an autopilot pullup when the pilot is not in control (not standby) and the system is supported without failures (not apfail).

Requirement Description

A requirement follows the sentence structure displayed below, where fields are optional unless indicated with "*". For information on a field format, click on its corresponding bubble.



FSM shall always satisfy (limits & autopilot) => pullup



Semantics

Always, the component "FSM" shall satisfy $((limits \ \& \ \text{autopilot}) \Rightarrow pullup)$.

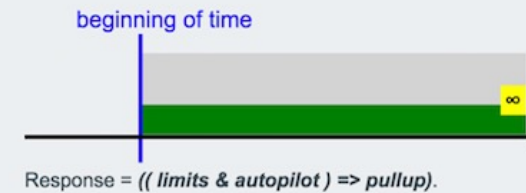


Diagram Semantics

Formalizations

Future Time LTL

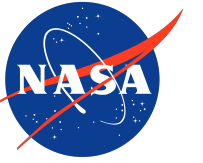
$G \ ((limits \ \& \ \text{autopilot}) \Rightarrow pullup)$

Target: *FSM* component.

Past Time LTL

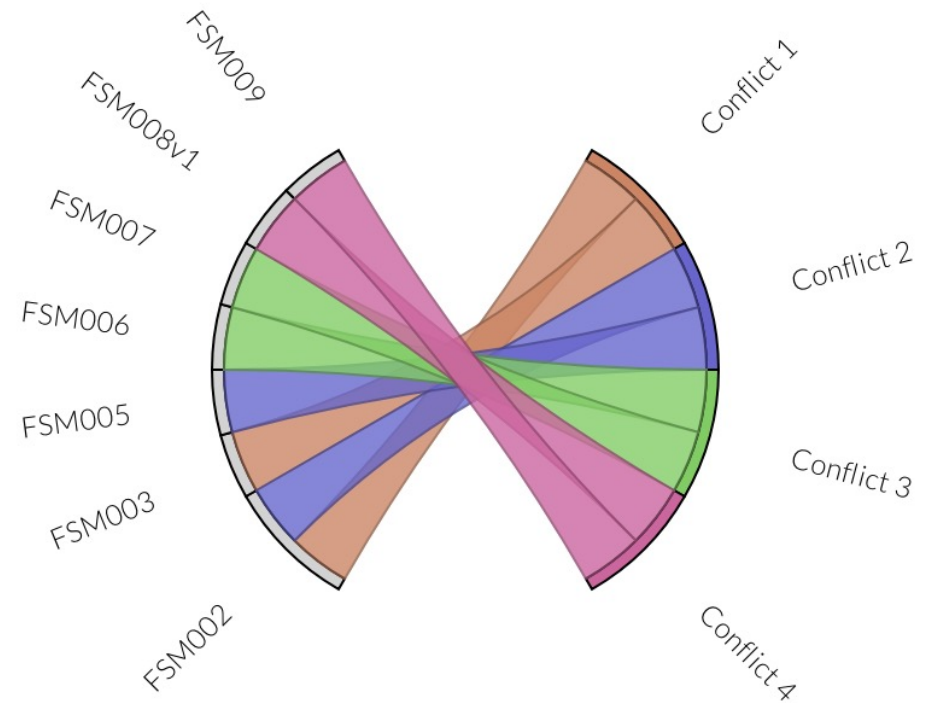
$((limits \ \& \ \text{autopilot}) \Rightarrow pullup) \ S \ (((limits \ \& \ \text{autopilot}) \Rightarrow pullup) \ \& \ \text{FTP})$

Target: *FSM* component.



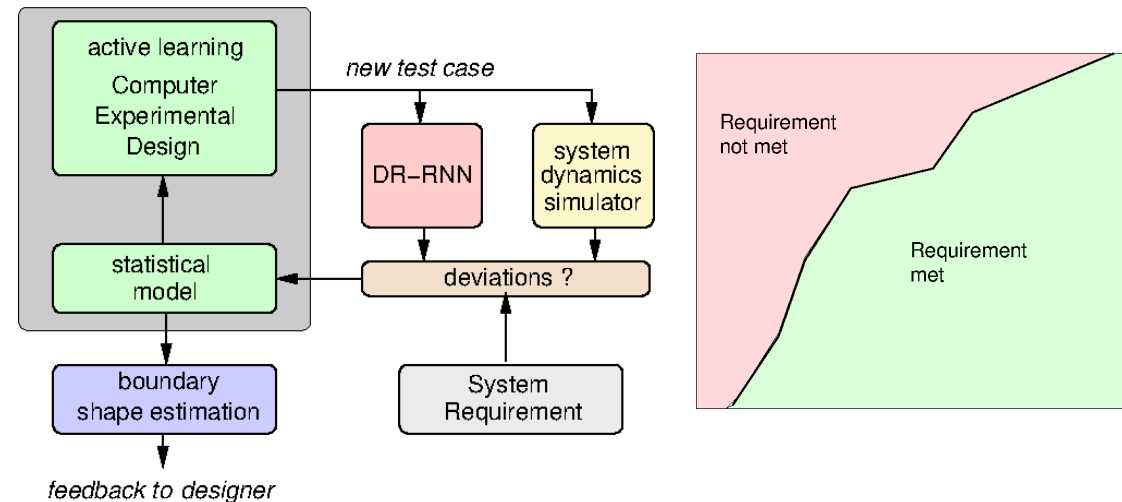
Formalizing Requirements

- Checking realizability of requirements, which aims at determining whether an implementation exists, always complying with a set of requirements, regardless of the stimuli provided by the system's environment.



Computing Safe Bounds of Operations

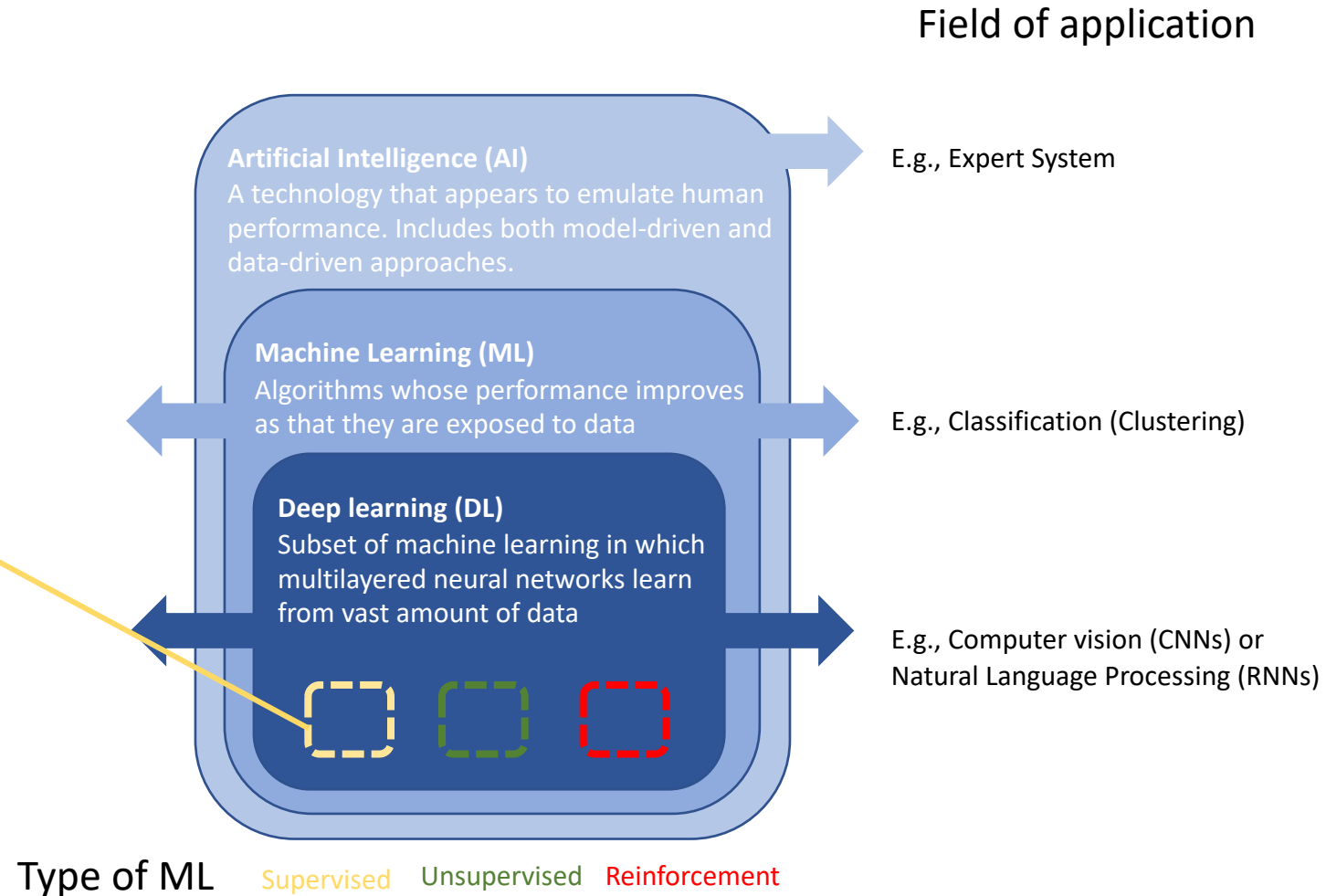
- Perturbations in the operational phase due to fluctuations in the data input and prediction output or in the model itself.
 - Use of SysAI (new branch of MARGInS) to evaluate the Taxinet example with noisy data.
- Perturbations in the design phase could also be found using SysAI.





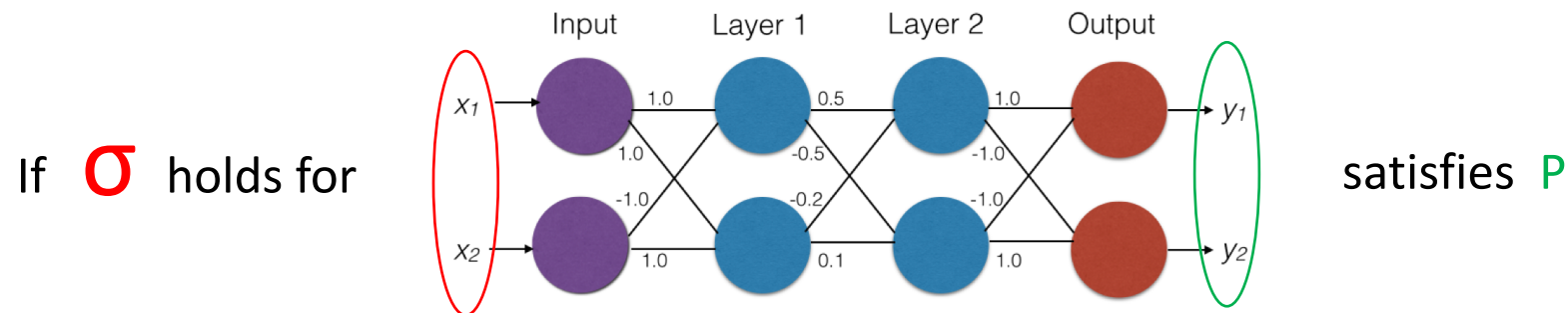
V&V of Machine Learning

- We focus mostly on off-line-trained, supervised DNNs
- Some of our results apply only to ReLU DNNs



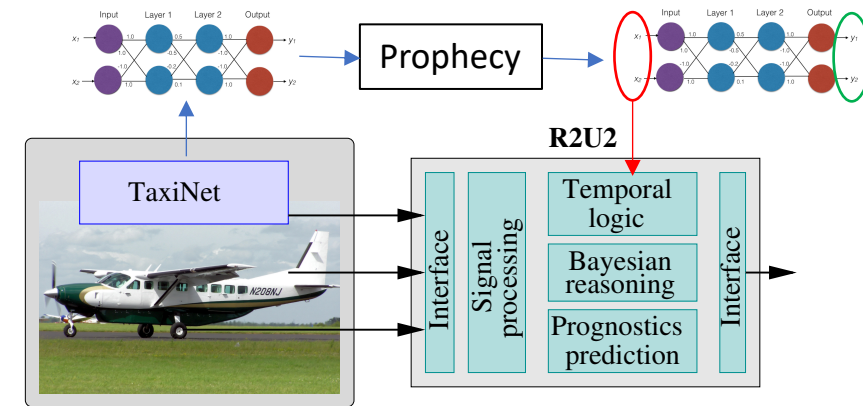
V&V of Machine Learning

- Prophecy Key Idea:
 - Infer “likely” properties, aka contracts, of a NN
 - Prove them using a decision procedure
- What is a contract? $\sigma \Rightarrow P$
 - σ is a precondition (“safe region”)
 - P is a postcondition; desired output behavior (e.g. some prediction)

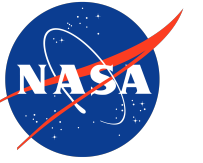


V&V Techniques Working together

- Use of runtime monitoring (R2U2 tool) to monitor inputs based on pre-conditions computed by Prophecy
 - Or by MARGInS or SysAI



- R2U2 is a run-time monitoring and V&V tool that combines Metric Temporal Logic observers, Bayesian Network reasoners, and model-based prognostics.
- FRET can also be used to generate formal monitors for R2U2 based on safety requirements.



Conclusions

- RSE is developing tools to make the software and system engineering processes more efficient.
- Most of the funding has been coming from ARMD, hence a focus on aviation systems
- Since we believe they make a difference, we are also injecting these tools in our small Sat missions
- We have created an internal mission called Troupe1, which we use to
 - Train new staff for missions
 - Evaluate the use of new tools and processes



Image courtesy of NASA Ames Research Center



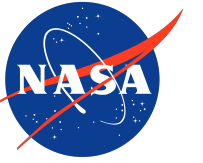
RSE Software Engineering Tools

| Tools | Description | Availability | Technical POC | POC Email |
|-----------------|---|-------------------|------------------------|---------------------------------|
| FRET | Requirement elicitation and analysis | Open Source | Dimitra Giannakopoulou | dimitra.giannakopoulou@nasa.gov |
| CoCoSim | Simulink model analyzer | Open Source | Khanh Trinh | khanh.v.trinh@nasa.gov |
| IKOS | Static code analysis for C/C++ | Open Source | Guillaume Brat | guillaume.p.brat@nasa.gov |
| AdvoCATE | Assurance case automation toolset | Open Source | Ewen Denney | ewen.w.denney@nasa.gov |
| MARGInS | ML/statistical libraries for system testing | Usage Agreement | Carlos Paradis | carlos.v.paradis@nasa.gov |
| SysAI | ML/statistical libraries for system testing | Not available yet | Yuning He | yuning.he@nasa.gov |



RSE Software Engineering Tools

| Tools | Description | Availability | Technical POC | POC Email |
|------------------|---|-------------------|------------------|-----------------------------|
| AdaStress | Adaptive stress testing | Open Source | Ritchie Lee | ritchie.lee@nasa.gov |
| RACE | Runtime for Airspace Concept Evaluation | Open Source | Peter Mehlitz | peter.c.mehlitz@nasa.gov |
| MESA | Run-time analysis of live data streams | Open Source | Nastaran Shafiei | nastaran.shafiei@nasa.gov |
| Prophecy | Formal analysis of Neural Networks | Not available yet | Corina Pasareanu | corina.s.pasareanu@nasa.gov |
| R2U2 | Vehicle-level run-time analysis | Usage Agreement | Johann Schumann | johann.m.schumann@nasa.gov |
| Drishti | NLP for requirement traceability | Not available yet | Nija Shi | nija.shi@nasa.gov |



Other Topics From Ames Research Center

TECHNICAL SESSIONS

- Mission Operations and Autonomy: *Design and Testing of Autonomous Distributed Space Systems*
- Science/Mission Payloads: *The Pandora SmallSat: Multiwavelength Characterization of Exoplanets and their Host Stars*
- Constellation Missions: *Design and Validation of an Autonomous Mission Manager towards Coordinated Multi-Spacecraft Missions*

NASA SHORT TALKS

- *Framework for Autonomous Planning of Distributed Space Systems*
- *How to Partner with NASA and Use Patented Technologies*
- *NASA Art in Space: A Rich History and The PACE-1 Flight Mission*
- *NASA Flight Opportunities: Competitive Access to Suborbital Flight Testing*
- *NASA SSTP's SmallSat Technology Partnerships for Universities*
- *Novel Communication Experiments in the Nano-Orbital Workshop (NOW) Series, Closing the Link to Geostationary Orbit with Automated Doppler Correction*